

PRODUCT INFORMATION PACKET

marathon®
Motors

Model No: 1009468-BR

Catalog No: 1009468

TerraMAX® Cast Iron Motor, 3 HP, 3 Ph, 60 Hz, 380 V, 900 RPM, 132S Frame, TEFC



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RegalRexnord

Nameplate Specifications

Output HP	3 Hp	Output KW	2.2 kW
Frequency	60 Hz	Voltage	380 V
Current	6.0 A	Speed	877 rpm
Service Factor	1.25	Phase	3
Efficiency	84.5 %	Power Factor	0.66
Duty	S1	Insulation Class	F
Frame	132S	Enclosure	Totally Enclosed Fan Cooled
Thermal Protection	No Protection	Ambient Temperature	40 °C
Drive End Bearing Size	6308	Opp Drive End Bearing Size	6208
UL	No	CSA	No
CE	No	IP Code	55
Number of Speeds	1		

Technical Specifications

Electrical Type	Squirrel Cage	Starting Method	Direct On Line
Poles	8	Rotation	Clockwise
Mounting	B3	Motor Orientation	Horizontal
Drive End Bearing	Zz C3	Opp Drive End Bearing	Zz C3
Frame Material	Cast	Shaft Type	Keyed
Overall Length	465 mm	Frame Length	202 mm
Shaft Diameter	38 mm	Shaft Extension	80 mm
Assembly/Box Mounting	TOP		
Outline Drawing	0213200610		

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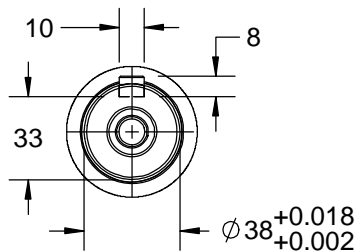
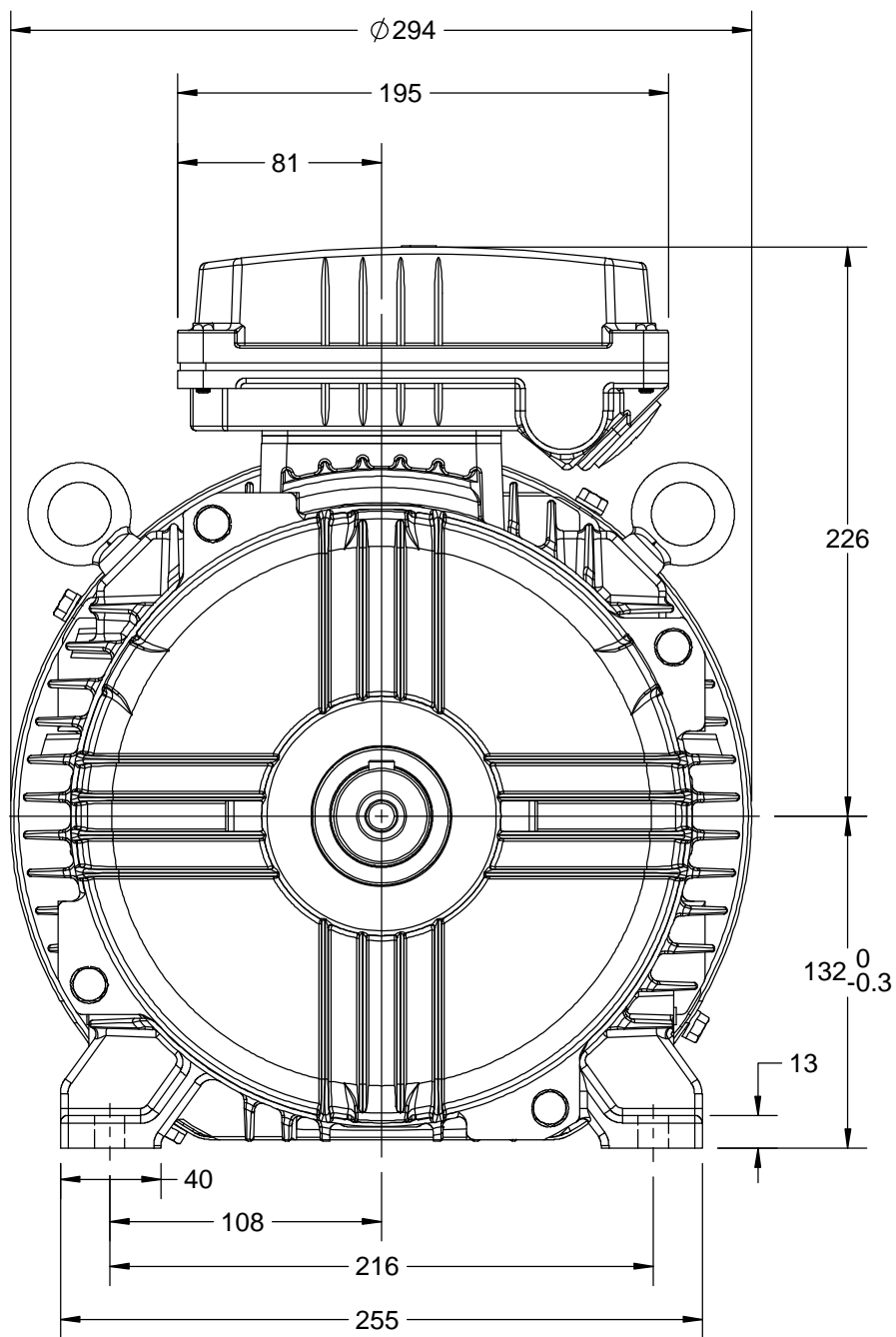
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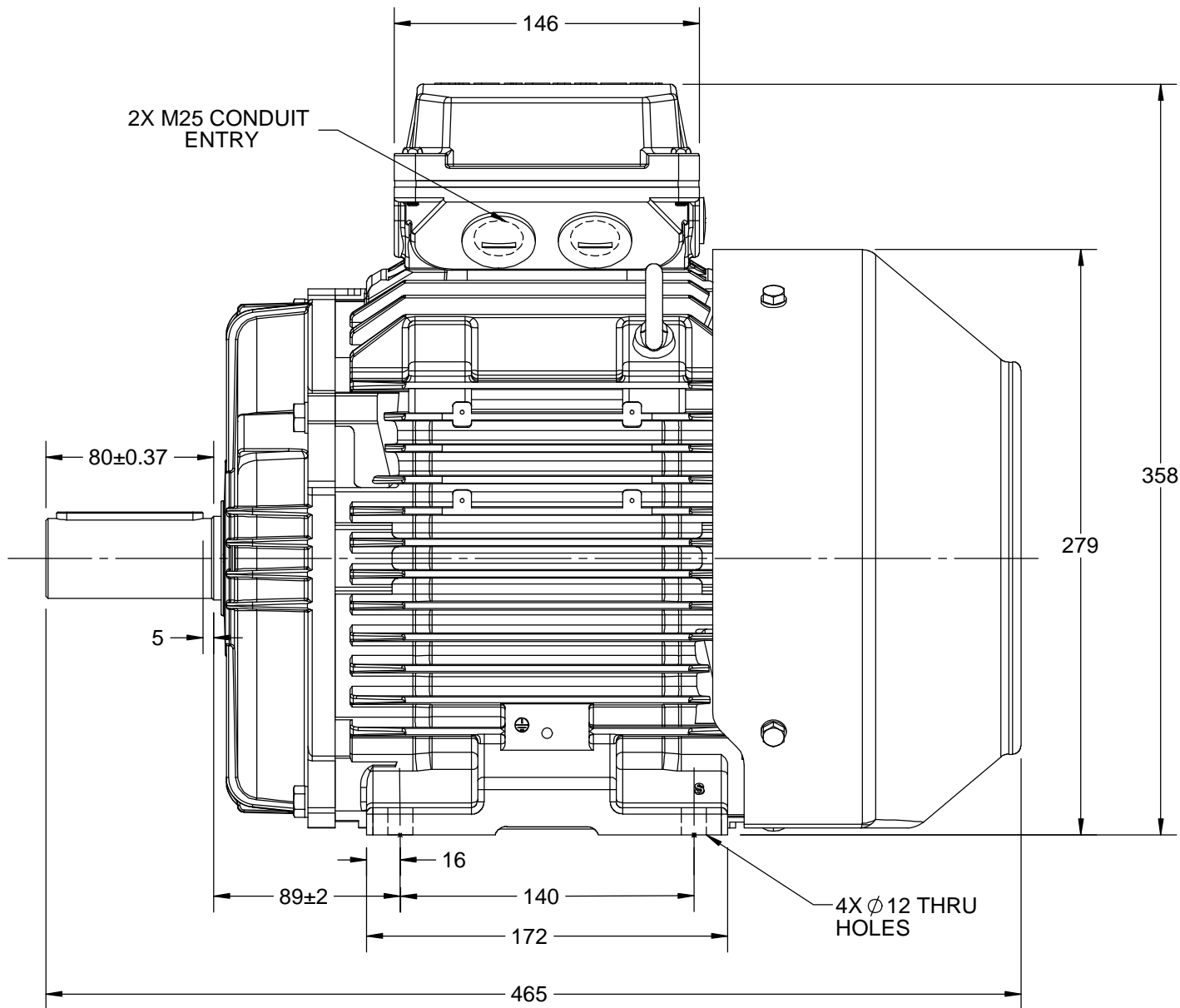
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2X M25 CONDUIT ENTRY



DRAWING REVISION C	REVISION BY S.MUDDA	DATE 26/06/2018
ECO ECO-0147359	APPROVED BY JAY	DATE 26/06/2018
ECO DESCRIPTION OUTLINE UPDATED AS PER NEW 3D STRUCTURING		
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DATE	10/11/2014
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THIRD ANGLE PROJECTION	

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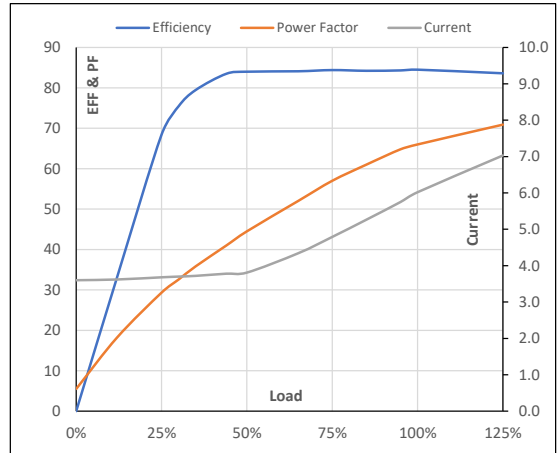
Model No. 1009468

Enclosure	U (V)	Δ / Y Conn	f [Hz]	P [kW]	P [hp]	I [A]	n [RPM]	T [kgm]	T [Nm]	IE Class	Amb [°C]	Duty	Elevation [m]	Inertia [kg-m ²]	Weight [kg]
TEFC	380	Δ	60	2.2	3	6.0	877	2.45	24.01	IR3	40	S1	1000	0.231	77

Motor Load Data

Load Point		NL	1/4FL	1/2FL	3/4FL	FL	5/4FL
Current	A	3.6	3.7	3.8	4.8	6.0	7.0
Torque	Nm	0.0	6.0	12.0	18.2	24.0	30.7
Speed	r/min	900	894	889	884	877	870
Efficiency	%	0.0	68.4	84.0	84.4	84.5	83.6
Power Factor	%	5.5	29.3	44.5	57.0	66.0	70.9

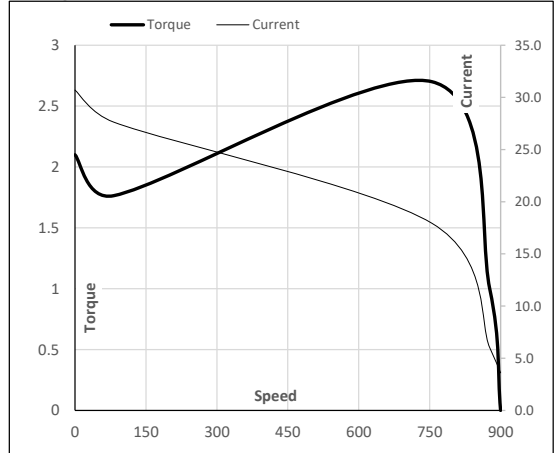
Performance vs Load Chart



Motor Speed Torque Data

Load Point		LR	P-Up	BD	Rated	NL
Speed	r/min	0	82	755	877	900
Current	A	30.7	27.6	17.9	6.0	3.6
Torque	pu	2.1	1.8	2.7	1	0

Starting Characteristics Chart



NOTE Refer data sheet for applicable standard and tolerances on performance parameters

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